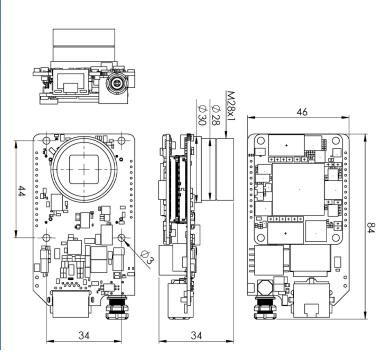
### VELOCIRAPTOR EVO





**Velociraptor EVO** is a highly customizable and user-programmable FPGA-based high-speed smart camera: the ultimate FPGA camera with a very large Xilinx Spartan-6 FPGA and high-speed imaging sensor. It is based on GigaBee modules which incorporate dual DD3 memory and Gigabit Ethernet. It features the ultimate-performance System-on-Chip (SoC) technology combined with the latest turbocharged industrial CMOS imaging sensor.

Velociraptor EVO includes a fully customizable and user-programmable open-reference design for a high-speed FPGA-based camera and application development system. Its emphasis is on an open-hardware/ software development model featuring high-frame rates, real-time image processing, ultra-large FPGA and modern graphical user interface support.

A suite of intermediate, versatile and large Xilinx Spartan-6LX150 FPGAs is used to develop algorithms and process data in real-time. Images are acquired by a AMS sensor, CMV2000 (2048x1088 pixels, 2/3" size) or CMV4000 (2048x2048 pixels, 1" size). The Sensor is very fast and outputs up to 768 million pixels per second resulting in 333 FPS (CMV2000) and 178 FPS (CMV4000) at full frame. The on-board 2x128MB DDR3 memory with 2x1.6GB/s of bandwidth enables usage of complex buffered image processing. A unique UDP based Ethernet protocol, developed especially for this camera, is used for communication with a PC. The camera is Ethernet powered (IEEE 802.3at PoE) with power consumption up to 10W. Velociraptor EVO cameras are suitable for demanding applications where extremely high-speed and high-frame rates are needed in combination with real-time image processing and adaptability to specific products or systems.

The Velociraptor EVO is targeted to Original Equipment Manufacturers (OEMs) who are seeking components that can be adapted to specific products or systems. The Velociraptor EVO camera provides a flexible framework of core capabilities that will serve as a platform for multimodal functionality. The framework is expandable, scalable and flexible to accommodate new algorithms and can be interoperable with existing systems. In two words, it's versatile and affordable, in all possible ways.

#### TARGETED FOR:

- Industrial process automation to count, detect, check, verify, read, inspect and test different products, levels, components etc.;
- Industrial quality control to inspect defects, cracks or surface blemishes, size, position, dimension and color, foreign objects and quality;
- Solar Cell Panel Inspection to inspect wafer, surface defects, glass, etc. and
- General R&D.

Velociraptor EVO							
Resolution	2.2 MP	4.2 MP					
Active Pixels (HxV)	2048 x 1088	2048 x 2048					
Frame Rate	331 FPS	176 FPS					
Sensor Format	2/3" CMOS	1" CM0S					
Pixel Size	5.5 µm	5.5 µm					
Sensor: AMS Image Sensor	CMV2000	CMV4000					
Interface	1 Gigabit Ethernet SFP+ for fast data transmission						
Programmable and Reconfigurable FPGA	Spartan-6LX150						

### **KEY CAMERA FEATURES**

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## **OPTO**MOTIVE

	CAMERA FAMILY VELOCIRAPTOR EVO								
	Camera Model	2.2M	2.2IR	2.2C	4.2M	4.2IR	4.2C		
-			CMV2000	1		CMV4000			
	Model (AMS)	2E5M1PP	E12M1PP	2E5C1PP	2E5M1PP	E12M1PP	2E5C1PP		
-	Color Filter	None	None	Bayer	None	None	Bayer		
	Diagonal		12.7 mm (2/3")			15.92 mm (1")			
ENSOR	Active Pixels	2048 x 1088 2048 x 2048							
	Pixel Size			5.5 um	x 5.5 um				
	Pixel Data Formats	5.5 μm x 5.5 μm MONO8 (M and IR), BAYER8 (C only)							
	Region of Interest	YES, with 8 pixel increments							
	Pixel Clock Speed								
	Frame Rate (Full Frame)	760 MHz (8 pixels @ 95 MHz)							
ר פ		331 FPS 176 FPS							
IMAGING SENSOR	RAW Frame Rate	54 FPS 26 FPS							
	ADC Resolution	10 bit							
	Analogue Gain	C mount holder without lens included							
	Analogue Gain	1-32x							
-	Digital Gain	Programmable look up table in FPGA							
	Shutter Type	Electronic global shutter							
-	Shutter Resolution	21 ns							
	Shutter Time	210 ns – 90 s							
	Exposure	Linear, 3 slope high dynamic range							
	Scanning System	Progressive							
FEATURES	Trigger Modes	Free running, trigger, overlap, pulse width							
	Trigger Features	Delay 0 – 1000 ms LP Filter 1.5Hz - 100 kHz							
	Dynamic Range	60 dB							
G	FPGA	Spartan6LX150							
SING	Free FPGA %	Up to 70%, most of the 180 slices of DSP are free.							
CES	Volatile Memory								
PROCI		2x 128 MB DDR3 SDRAM							
₽	Non-volatile Memory	8MB flash							
	Lens Mount	C-mount (1" 32G thread)							
GAL CAL	Temp Range	0 - 50°C							
MECHANICAL	Mass Protection	50 g OEM / 290 g with housing							
CHZ	Housing Material	Up to IP67 with housing							
Ξ	RoHS	CNC-machined aluminum, anodized in a special OptoMotive blue color RoHS compliant							
	Fixing Holes	4 x M3 0EM / 2 x M6 with housing							
_	Input Voltage	Power over Ethernet, 42-57V							
ELECTRICAL	Consumption	Up to 10W							
LR.	10	3x bidirectional							
ц Ч	IO Isolation	No, but camera has 1.5kV PoE isolation							
Ē	Connectors	RJ45, 4 pin LEMO EXG 00 304							
	On-board Image Processing	As an option (if an IP core is integrated)							
μ Π	IP Cores	Yes. Can be implemented into the camera additionally. See the List of IP cores available.							
	Open Reference Design	Yes							
Z	Open Architecture	Yes							
FUNCTIONALITIES	Software	Compatible with OptoMotive VEVO software (full source code included)							
ž	Operating System	Windows 7, Windows 10, 64bit or 32bit							
щ	Development Tools	Xilinx ISE/EDK version 13.3 or later, Microsoft Visual Studio 2010							

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